

## Statistics for Astronomers: Lecture 2, 2020.09.23

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## Review

Probability: Classical vs. Frequentist vs. Bayesian.
Kolmogorov Axioms.
Conditional and marginal probability.
Independence and exclusivity.
Law of Total Probability from union of pairwise disjoint, collectively exhaustive sets.
Bayes' Theorem.

## Random variables and probability distributions

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## Convention:

$X$ : random variable, $x$ : value assigned to random variable.
"Probability that $X$ has value $x$ ": $P(X=x), P_{x}(x)$ ( $x$ discrete) or $p_{x}(x)$ ( $x$ continuous).
Specifying $P_{x}(x)$ or $p_{x}(x)$ for all $x \in S$, the state space results in a probability distribution.
Discrete: mass function (PMF). Continuous: density function (PDF).
Note: I won't abbreviate "probability distribution function", so that "PDF" is unambiguous.

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$P_{x_{3}}\left(x_{3}\right)=\sum_{x_{2} \in S} \sum_{x_{1} \in S} P\left(X_{3}=x_{3} \mid X_{2}=x_{2}, X_{1}=x_{1}\right) P\left(X_{2}=x_{2} \mid X_{1}=x_{1}\right) P\left(X_{1}=x_{1}\right)$

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The state $X_{3}=0$ ( "third ball is red" ) can be achieved in three ways (see $\Omega$ ).

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$$
\begin{aligned}
P\left(X_{3}=0\right) & =P\left(X_{3}=0 \mid X_{2}=1, X 1=0\right) P\left(X_{2}=1 \mid X_{1}=0\right) P\left(X_{1}=0\right) \\
& +P\left(X_{3}=0 \mid X_{2}=0, X 1=1\right) P\left(X_{2}=0 \mid X_{1}=1\right) P\left(X_{1}=1\right) \\
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& =\frac{2}{10} \cdot \frac{8}{9} \cdot \frac{1}{8}+\frac{8}{10} \cdot \frac{2}{9} \cdot \frac{1}{8}+\frac{8}{10} \cdot \frac{7}{9} \cdot \frac{2}{8}=\frac{1}{5}
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& \Longrightarrow P\left(X_{3}=1\right)=1-P\left(X_{3}=0\right)=\frac{4}{5} .
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(Tim Stellmach/Public Domain)

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$P(X=4)$ makes sense, is finite.
$P(4 \leq X \leq 7)=\sum_{i=4}^{7} P(X=i)=\frac{18}{36}=\frac{1}{2}$.

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(Tim Stellmach/Public Domain)

Actual departure time of Flight 1522 (continuous distribution):

$$
\text { State space }=(5.4, \infty)
$$



Shaded region $=P(8: 00 \mathrm{AM}<T<8: 44 \mathrm{AM})$.
$P(X=8: 15 \mathrm{AM})$ is meaningless, zero.
$P(8: 00 \mathrm{AM}<T<8: 44 \mathrm{AM})=\int_{8: 00 \mathrm{AM}}^{8: 44} p_{x}(x) d x$ is finite.

## Populations and samples

If a random variable $X$ has probability distribution is $P_{X}(x)$ (discrete) or $p_{x}(x)$ (continuous), we say that $X$ is drawn from the PMF/PDF: $X \sim P_{X}(x)$ or $X \sim p_{x}(x)$.

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Experiment performed a finite number of times; sample unable to faithfully reproduce the population - statistics (quantities derived from the sample) are only guesses at (estimates of) the corresponding parameters (values that describe the population).
Convention: Greek symbols for parameters (e.g., $\mu, \sigma$ ), Latin symbols for statistics (e.g., $\bar{x}, s$ ).

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"More data is required."

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Sample distribution seems uniform, results in a larger sample mean/variance than the true (population) values.

## Cumulative distribution function (CDF)

## Definition (Cumulative distribution function)

A function $F_{X}(x)$ of a random variable $X$ such that $F_{X}(x)$ is the probability that $X \leq x$. For a discrete PMF:

$$
F_{X}(x)=P(X \leq x)=\sum_{x_{i} \leq x} P\left(X=x_{i}\right) .
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For a continuous PDF:

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From this definition, the probability of the variable ranging between two values $a$ and $b$ is $P(a<X \leq b)=F_{X}(x=b)-F_{X}(x=a)$. For a PDF, this is also equal to $\int_{t=a}^{t=b} p_{X}(t) d t$.

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The CDF is a monotonically increasing function.
For a discrete random variable, it is constant in between values.
For the continuous case, the PDF is the derivative of the CDF w.r.t. $x$.

## Cumulative distribution function (contd.)

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The inverse of the CDF, a function $Q(p)$ that returns the value of $x$ such that $F_{X}(X \leq x)=p$.

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## Definition (Independent and identically distributed variables)

Two random variables $X$ and $Y$ are said to be iid if and only if they are mutually independent and drawn from the same distribution:

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\begin{gathered}
F_{X, Y}(x, y)=F_{X}(x) \times F_{Y}(y) \\
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Heteroskedastic: originally iid observations + measurement errors that aren't identical.
Typical case in astronomy.

## Expectation value

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The expectation value $E[g(X)]$ of a function $g(X)$ of a random variable $X$, is the weighted average of $g(X)$, with the weights being the associated probabilities:
Discrete: $E[g(X)]=\sum_{i=1}^{N} g\left(x_{i}\right) P\left(X=x_{i}\right)$.

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Linearity: $E[\alpha g(X)+\beta h(X)]=\alpha E[g(X)]+\beta E[h(X)] . \quad$ ( $\sum$ and $\int$ are linear operators!) Independence: $X \perp Y \Longrightarrow E[X Y]=E[X] E[Y]$.

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Why the square? What is $E[X-E(X)]$ ?
The expression for the variance can be simplified: $\operatorname{Var}[X]=E\left[X^{2}\right]-(E[X])^{2}$.
Note: When no other function is specified, "expectation value" refers to the mean, $E(X)$.

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$-\operatorname{Var}(\alpha X)=\alpha^{2} \operatorname{Var}(X)$.
(3) For constants $\alpha, \beta$ and random variables $X, Y$,
$\operatorname{Var}(\alpha X+\beta Y)=? ?$
Evaluate this expression using the definition of variance in terms of expectation values.


## Covariance

> interpretation?
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Therefore, $\operatorname{Var}(\alpha X+\beta Y)=\alpha^{2} \operatorname{Var}(X)+\beta^{2} \operatorname{Var}(Y)+2 \alpha \beta \operatorname{Cov}(X, Y)$.
If the two variables are uncorrelated, then the third term vanishes.

## Correlation coefficient

The sign of $\operatorname{Cov}(X, Y)$ probes a linear relationship between the two variables $X$ and $Y$.

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By definition, $\rho_{X X}=1$. "Perfect correlation". $\rho_{X X}=-1$ : "perfect anticorrelation".

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$X_{1}, X_{2}$ : random variables for the values on the $1^{\text {st }}$ and $2^{\text {nd }}$ die after each throw, we record $X_{1}+X_{2}$ each time.

Variance on a single measurement of this sum $=5.83$.
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As \# measurements $N \uparrow$, variance on the mean of $N$ measurements $\downarrow$.
Sample mean approaches population mean.
See Law of Large Numbers.

## Some common probability distributions

## Attributes of probability distributions via Python/Scipy

(See documentation for each distribution in scipy.stats)

- rvs - random variates (sample from the distribution)
- pmf/pdf - PMF or PDF
- logpmf/logpdf - log of the PMF or PDF
- cdf - CDF
- logcdf - log of the CDF
- ppf - percent point function (inverse of cdf; percentiles)
- stats - Mean('m'), variance('v'), skew('s'), kurtosis('k')
(also see mean, median, var, std)
- expect - Compute expectation value of a function of this random variable
- interval - Confidence interval


## Bernoulli (discrete; scipy.stats.bernoulli)

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Generate 10 samples from scipy.stats.bernoulli:
from scipy.stats import bernoulli
$\mathrm{p}=0.25$ \#probability of success
print(bernoulli.rvs(p, size = 10)) \#10 random deviates
[0 $000 c 11000000]$ \#possible output

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Compute probability of 2 successes in 10 trials

```
from scipy.stats import binom
n, k, p = 10, 2, 0.25 #total trials, num successes, prob of 1 success
print(binom.pmf(k, n, p)) #prob of k successes in n trials
```

0.28156757354736334 \#output

## Expectation value of a Binomial Distribution

Recall:

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(x+y)^{n}=\sum_{k=0}^{n}\binom{n}{k} x^{k} y^{n-k} \tag{2}
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\end{aligned}
$$

## Expectation value of a Binomial Distribution

Recall:

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(x+y)^{n}=\sum_{k=0}^{n}\binom{n}{k} x^{k} y^{n-k} \tag{2}
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Expectation value for the binomial distribution:

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E(X) & =\sum_{k=0}^{n} k\binom{n}{k} p^{k}(1-p)^{n-k}=\sum_{k=1}^{n} k\binom{n}{k} p^{k}(1-p)^{n-k}(k=0 \text { term vanishes) } \\
& =\sum_{k=1}^{n} n\binom{n-1}{k-1} p^{k}(1-p)^{n-k} & \text { using Eq. (3) } \\
& =\sum_{s=0}^{n-1} n\binom{n-1}{s} p^{s+1}(1-p)^{n-s-1} & \text { (setting } s=k-1) \\
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Similarly, we can compute $\operatorname{Var}[X]$ using $k(k-1)\binom{n}{k}=n(n-1)\binom{n-2}{k-2}$

