



# Statistics for Astronomers: Lecture 6, 2020.10.14

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# Review

Frequentist statistical inference:

Parametric (specify model, compute likelihood) vs.  
nonparametric (performed on rank-ordered data).

Estimation (point/interval) or hypothesis testing.

Bayesian vs frequentist inference.

Statistics and their desired properties.

Estimators, estimates. Bias-variance tradeoff.

Point estimates: likelihood.

# Maximum Likelihood Estimation

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$$\frac{\partial}{\partial \theta} \ln \mathcal{L}(\theta) = \frac{8}{\theta} - \frac{2}{1 - \theta}; \quad \text{vanishes at } \theta = \hat{\theta}_{\text{MLE}} \implies \hat{\theta}_{\text{MLE}} = \mathbf{0.8}.$$

# MLE for iid Gaussian random variables

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MLE of  $\sigma^2$  is the (biased) sample variance!

# What is the uncertainty on the MLE?

Coin-toss problem: assume that the true  $\theta$  is  $\theta_0 = 0.8$ , unknown to observer.

Each round of ten tosses: different value of  $\hat{\theta}_{\text{MLE}}$  (e.g., [0.9, 0.7, 0.9, 0.8, 1., 0.9, 1., 0.9, 0.9, 0.8]).

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Expand  $\ln \mathcal{L}$  around  $\theta_0$ :

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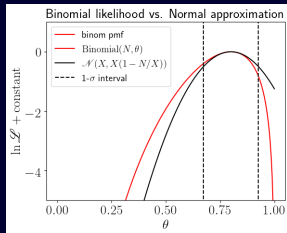
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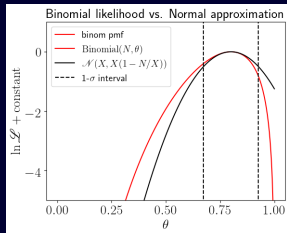
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Curvature defined as the negative second derivative of  $\ln \mathcal{L}$  at location of maximum:

$$I(\theta) \equiv -\frac{\partial^2}{\partial \theta^2} \log \mathcal{L} \quad (\text{1-D})$$

$$I_{ij}(\vec{\theta}) \equiv -\frac{\partial}{\partial \theta_i} \frac{\partial}{\partial \theta_j} \log \mathcal{L} \quad (\text{N-D}) \quad \text{Fisher information matrix.}$$

Large curvature near  $\vec{\theta}_0$ : less uncertainty (more information) about location of maximum.

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The inverse of the Expected Fisher matrix is the **covariance matrix** of the parameters:

$$\Sigma(\vec{\theta}) = \mathcal{I}^{-1}(\vec{\theta})$$

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Experiment: Ten coin tosses with unknown probability  $\theta$  of obtaining a head.

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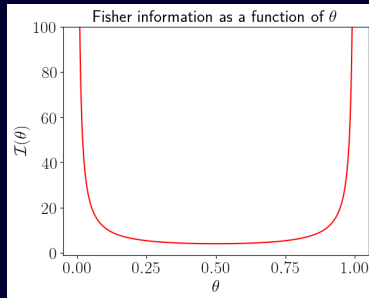
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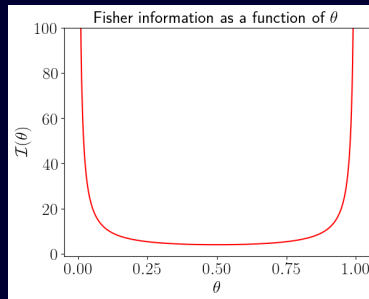
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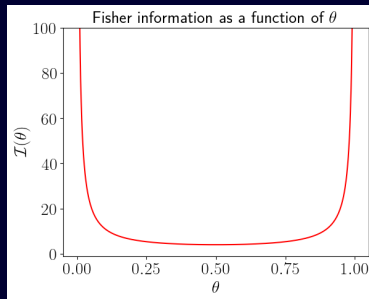
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Is this always true? **Cramér-Rao Lower Bound**.



Code for plot available [here](#)

# Variance of unbiased estimators: Cramér-Rao Lower Bound

If  $\vec{T}(X)$  is an unbiased estimator of a function  $\vec{g}(\vec{\theta})$  of the parameters  $\vec{\theta}$  (i.e.,  $\mathbb{E}[\vec{T}(X)] = \vec{g}(\vec{\theta})$ ), and  $\mathcal{I}(\vec{\theta})$  is the expected Fisher information matrix, then



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For biased estimators: If  $\mathbb{E}[\vec{\mathbf{T}}(X) - \vec{\theta}] = \vec{B}(\vec{\theta}) \neq 0$ , set  $\vec{g}(\vec{\theta}) = \vec{B}(\vec{\theta}) + \vec{\theta}$  and apply CRLB.

# Covariance matrix for MLE of Gaussian random variables

Recall:

$$\frac{\partial \ell}{\partial \mu} = \sum_{i=1}^N \left( \frac{x_i - \mu}{\sigma^2} \right) \quad \frac{\partial \ell}{\partial \sigma} = \frac{1}{\sigma} \left( -N + \sum_{i=1}^N \frac{(x_i - \mu)^2}{\sigma^2} \right) \quad \mathbb{E} \left[ \sum_{i=1}^N (x_i - \mu)^2 \right] = N \sigma^2$$

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# Computational MLE

Log-likelihood is fed to routine by user.

Routine optimises this function using a variety of techniques.

The output will include the MLE as well as the covariance matrix.

Example: fitting a line to data with uncertainties.

# Point estimation: caveats (Feigelsen & Babu, ch. 3)

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- 1 **Model specification:** required to compute the likelihood. How do we know it is correct?  
Model validation (goodness-of-fit).  
Model selection.
- 2 **Estimation method:** which estimator do we pick?  
The MLE is not always unbiased.  
Minimum Variance Unbiased Estimator (MVUE) – among unbiased estimators, pick the one with the least variance.