



Statistics for Astronomers: Lecture 7, 2020.10.19

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Review

Maximum likelihood estimation.

The variance of the MLE: Fisher information, covariance matrix.

Variance of unbiased estimators: The Cramér-Rao Lower Bound.

The minimum variance unbiased estimator (MVUE).

The χ^2 distribution

References

▶ "Dos and don'ts of reduced chi-squared". Andrae, Schulze-Hartung, & Melchior.

▶ "Error estimation in astronomy: A guide". Andrae.

χ^2 minimisation

\vec{Y} : a random vector dependent on a non-random^R vector \vec{X} .

\vec{y} : a measurement of \vec{Y} .

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χ^2 (sometimes a.k.a. "log-likelihood") is a sum of squares of Standard Normal residues.

Has a $\chi^2(\nu = N)$ distribution ($\nu = \text{dof}$). \mathcal{L} is max when χ^2 is min – " χ^2 minimisation".

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χ^2 is the MLE only if the errors are Gaussian! Check this with your data!

e.g., compute residues and verify that they are normally distributed (see Sec 4.1 [here](#)).

Navigation icons: back, forward, search, etc.

The χ^2 distribution

If $Z \sim \mathcal{N}(0, 1)$ and $W = Z^2$,

$$\begin{aligned} p_W(w) &= p_Z(\sqrt{w}) \frac{dz}{dw} = 2 \frac{1}{\sqrt{2\pi}} e^{-\frac{w}{2}} \frac{1}{2\sqrt{w}} \\ &= \frac{w^{-1/2}}{\Gamma\left(\frac{1}{2}\right)} e^{-\frac{w}{2}} \quad (w > 0) \equiv \chi^2(\nu = 1). \end{aligned}$$

Recall: $\mathbb{E}[Z^2] = \mu^2 + \sigma^2 = 1$.

χ^2 distribution for 1 dof. Mean: 1, variance: 2.

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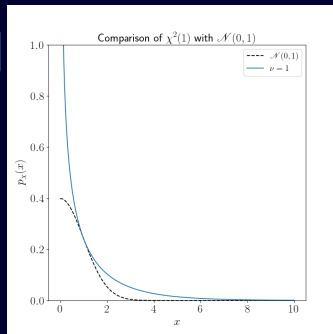
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Code for plot available [here](#).



Same mean, but steeper distribution near 0 and wider tails.

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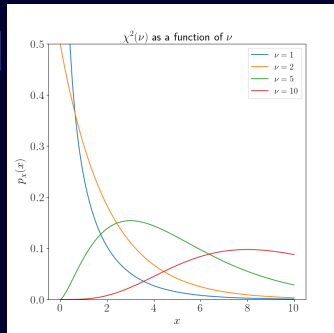
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Since $x > 0$, asymmetric!

$\chi^2(\nu = N) \rightarrow \mathcal{N}(N, 2N)$ as $N \rightarrow \infty$.

But takes a while! Needs large N .

Example of inference from χ^2 minimisation

Assume a linear model: $y_{\text{mod}}(x_i; \vec{\theta}) = m x_i + b$, so that $\chi^2 = \sum_{i=1}^N \left(\frac{y_i - m x_i - b}{\sigma_i} \right)^2$.

Compute derivatives wrt m and b and set to zero to solve for the parameters:

$$\frac{\partial \chi^2}{\partial b} = -2 \sum_{i=1}^N \frac{y_i - m x_i - b}{\sigma_i^2}; \quad \frac{\partial \chi^2}{\partial m} = -2 \sum_{i=1}^N x_i \left(\frac{y_i - m x_i - b}{\sigma_i^2} \right)$$

$$\hat{m} \sum_{i=1}^N \frac{x_i^2}{\sigma_i^2} + \hat{b} \sum_{i=1}^N \frac{x_i}{\sigma_i^2} = \sum_{i=1}^N \frac{x_i y_i}{\sigma_i^2} \quad \hat{m} \sum_{i=1}^N \frac{x_i}{\sigma_i^2} + \hat{b} \sum_{i=1}^N \frac{1}{\sigma_i^2} = \sum_{i=1}^N \frac{y_i}{\sigma_i^2}$$

$$\vec{\theta} = A^{-1}B; \quad \theta = (m, b)^T \quad B \equiv \left(\sum_{i=1}^N \frac{x_i y_i}{\sigma_i^2}, \sum_{i=1}^N \frac{y_i}{\sigma_i^2} \right)^T \quad A \equiv \begin{bmatrix} \sum_{i=1}^N \frac{x_i^2}{\sigma_i^2} & \sum_{i=1}^N \frac{x_i}{\sigma_i^2} \\ \sum_{i=1}^N \frac{x_i}{\sigma_i^2} & \sum_{i=1}^N \frac{1}{\sigma_i^2} \end{bmatrix}$$

A can be inverted numerically to solve for the parameters $\vec{\theta}$.
Parameter uncertainties from covariance matrix.

Interpretation of χ^2 and reduced χ^2 values

χ^2 minimisation produces ML estimates (and thus constraints) for p parameters.

#dof $\nu = N - p$. $\mathbb{E}[\chi^2(\nu)] = \nu$; $\text{Var}[\chi^2(\nu)] = 2\nu$. Relative error: $\sqrt{\frac{2}{\nu}} \approx 14\%$ even for $N = 100$.

$\chi^2(\nu) > \nu$: **underfitting**; errors underestimated. $\chi^2(\nu) < \nu$: **overfitting**; errors overestimated.

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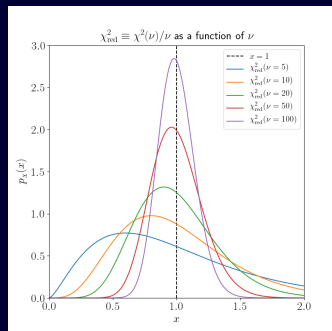
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ν -dependent shape; highly asymmetric for $\nu \lesssim 30$.

Code for plot available [here](#)

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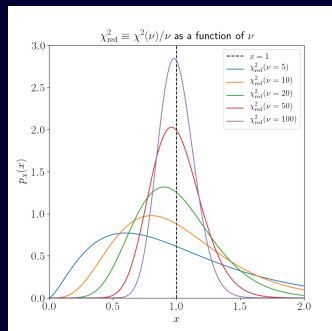
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Typical practice: $\chi_{\text{red}}^2 \approx 1$: good fit.

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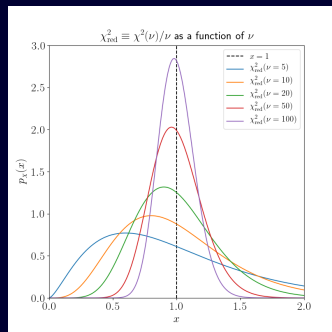
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Problem: huge relative uncertainty ($\sim 100\%$) **even for a perfect model!**

#dof not easy to define in many situations!

See [Dos and dont's for reduced \$\chi^2\$](#) for more.



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The normal and Student's t distributions

The multivariate normal distribution

An N -dimensional generalisation of the normal distribution. Rewrite the pdf for the 1-D case:

$$\begin{aligned} p_X(x) &= \frac{1}{\sqrt{2\pi\sigma^2}} \exp \left[-\frac{1}{2} \left(\frac{x - \mu}{\sigma} \right)^2 \right] = \frac{1}{\sqrt{2\pi\sigma^2}} \exp \left[-\frac{1}{2} (x - \mu) \left(\frac{1}{\text{Var}[X]} \right) (x - \mu) \right] \\ &= \frac{1}{(2\pi\sigma^2)^{1/2}} \exp \left[-\frac{1}{2} (x - \mu) \left(\frac{1}{\text{Cov}(X, X)} \right) (x - \mu) \right]. \end{aligned}$$

The N -D case can be summarised using the (column) vector \vec{X} and the **covariance matrix** Σ .

$$\vec{X} = (X_1, X_2, \dots, X_n), \text{ such that } (\vec{X})_i = X_i.$$

$$\Sigma = \text{Cov}(\vec{X}, \vec{X}), \text{ such that } (\Sigma)_{ij} = \text{Cov}(X_i, X_j) = E[(X_i - E[X_i])(X_j - E[X_j])].$$

$$\Sigma = E[(\vec{X} - E[\vec{X}])(\vec{X} - E[\vec{X}])^T] \text{ (the transpose generates a matrix of the proper shape).}$$

The **multivariate normal distribution** is, therefore,

$$p_{\vec{X}}(\vec{x}) = \frac{1}{\left((2\pi)^N \text{Det}(\Sigma) \right)^{1/2}} \exp \left[-\frac{1}{2} (\vec{x} - \vec{\mu}) \Sigma^{-1} (\vec{x} - \vec{\mu})^T \right], \text{ with } \vec{\mu} \equiv E[\vec{X}].$$

The covariance matrix has the effect of “mixing” terms together.

Bivariate normal: $N = 2$ case of multivariate normal

Recall: $\text{Cov}(X, Y) = \rho\sigma_X\sigma_Y$, with correlation coefficient ρ and σ_i the standard deviation of X_i .

$$\Sigma = \begin{bmatrix} \text{Cov}(X, X) & \text{Cov}(X, Y) \\ \text{Cov}(Y, X) & \text{Cov}(Y, Y) \end{bmatrix} = \begin{bmatrix} \sigma_X^2 & \rho\sigma_X\sigma_Y \\ \rho\sigma_Y\sigma_X & \sigma_Y^2 \end{bmatrix} \implies \text{Det}(\Sigma) = (1 - \rho^2)\sigma_X^2\sigma_Y^2$$

$$\underbrace{p_{\vec{x}}(\vec{x})}_{P(X \cap Y)} = \frac{1/(2\pi)}{\sqrt{\sigma_X\sigma_Y(1-\rho^2)}} \exp \left[-\frac{1}{2(1-\rho^2)} \left(\underbrace{\left(\frac{x-\mu_X}{\sigma_X}\right)^2}_{P(X)} + \underbrace{\left(\frac{y-\mu_Y}{\sigma_Y}\right)^2 - 2\rho\left(\frac{x-\mu_X}{\sigma_X}\right)\left(\frac{y-\mu_Y}{\sigma_Y}\right)}_{P(Y|X)} \right) \right]$$

In general, $\rho \neq 0$, so $P(Y|X) \neq P(Y)$.

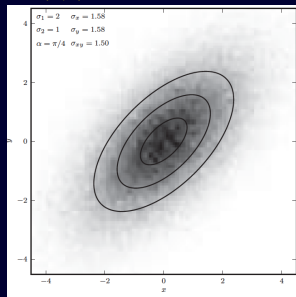
Uncorrelated X_i : $\Sigma = \text{Diag}(\sigma_1^2, \dots, \sigma_N^2)$; $\text{Det}(\Sigma) = \prod_{i=1}^N \sigma_i^2$.

Multivariate version visualised as the joint distribution

$$\begin{aligned} &P(X_1, X_2, \dots, X_N) = \\ &P(X_1) \cdot P(X_2|X_1) \cdot P(X_3|X_2, X_1) \cdots P(X_N|X_1, X_2, \dots, X_{N-1}) \end{aligned}$$

Contours showing linear correlation between σ_X and σ_Y : \longrightarrow

Non-linear correlation would result in “banana-shaped” contours.



Hess diagram of a bivariate normal (AstroML, Chapter 3.)

Why do I need the multivarlahblahblah?

Example: χ^2 fits to spectral energy distributions (SEDs) and spectra.

SEDs consist of observations in broadband photometric filters. There is sometimes quite an overlap between adjacent filters, which means the corresponding fluxes/uncertainties in those bands are **correlated**.

Spectra are even worse – very narrow wavelength range for each point, and adjacent points are almost certainly correlated.

A more general model of spectra/SEDs would account for these effects with non-diagonal covariance matrices, for example.

However, this can only describe linear correlations (not “banana-shaped” contours).

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Subtract the location parameter/statistic and divide by the scale parameter/statistic.

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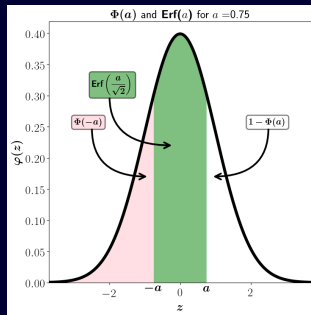
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$P(|Z| < a)$ – probability enclosed within some distance of the centre of the distribution.

$P(|Z| > a)$, $P(Z < -a)$, $P(Z > a)$ – probability of encountering extreme values (**one/two-tailed**).



Code for plot available [here](#)

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$$\text{Central probability: } P(|Z| \leq a) = \Phi(a) - \Phi(-a) = \text{erf}\left(\frac{a}{\sqrt{2}}\right).$$

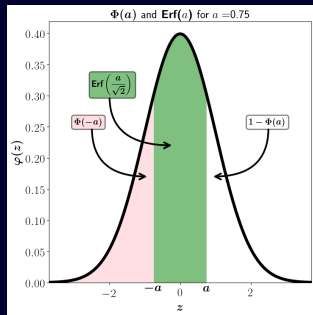
$$\text{One-tailed extreme: } P(Z \leq -a) = \Phi(-a), \text{ CDF of } \mathcal{N}(0, 1).$$

$$\text{Two-tailed extreme: } |Z| > a \implies (Z < -a) \text{ or } (Z > a).$$

$$P(|Z| > a) = 1 - P(|Z| < a) = 1 - \text{erf}\left(\frac{a}{\sqrt{2}}\right).$$

Where **erf** is the **error function**:

$$\text{erf}(x) \equiv \frac{1}{\sqrt{2\pi}} \int_{-x\sqrt{2}}^{x\sqrt{2}} dt e^{-t^2/2} = \frac{1}{\sqrt{\pi}} \int_{-x}^x dt e^{-t^2}.$$



Code for plot available [here](#)

Practice

Use `scipy.special.erfinv` or methods from `scipy.stats.norm` to find

1. Central probability: a such that $P(|Z| < a) = 0.5$
2. One-tailed extreme: a such that $P(Z < -a) = 0.1$
3. Two-tailed extreme: a such that $P(|Z| > a) = 0.995$